

I'm not robot  reCAPTCHA

Continue

This is a code repository for neural network projects with Python, published by Packt. The ultimate guide to using Python to explore the true power of neural networks through six projects What is this book about? Neural networks are at the heart of AI's latest advances, providing some of the best solutions to many real-world problems, including image recognition, medical diagnosis, text analysis and more. This book runs through some basic neural network and deep learning concepts as well as some popular libraries in Python to implement them. This book covers the following interesting features: Learn the different architectures of neural networks and its achievements in AI Master deep learning at Python by creating and learning the neural network of Master Neural Networks for Regression and Classification Discover a sentient neural network for image recognition Learn to analyze the moods on text data using long-term short-term memory If you feel this book is for you, get a copy today! Instructions and navigation All code is organized in folders. For example, Chapter 02. The code will look like this: def detect\_faces (img, draw\_box grayscale\_img=True): COLOR\_BGR2GRAY) Below is what you need for this book: This book is perfect for data scientists, machine learning engineers, and deep learning enthusiasts who want to create practical neural network projects at Python. Readers should already have some basic knowledge of machine learning and neural networks. With the following software and hardware list, you can run all the code files present in the book (Chapter 1-7). Software and Hardware List Chapter Software requires os requiring 1-7 Python, Jupyter Laptop Windows, Mac OS X, and Linux (Anyone) We also provide a PDF file that has color image screenshots/diagrams used in this book. Click here to download it. Related Products Get To Know author James Loy has more than five years of expertise in data science in finance and health. He worked with the largest bank in Singapore to drive innovation and increase customer loyalty through predictive analytics. He also has experience in the health sector, where he has applied data analytics to improve decision-making in hospitals. He holds a master's degree in computer science from Georgia Tech, specializing in machine learning. His research interest includes deep learning and applied machine learning, as well as the development of AI computer agents for automation in the industry. He writes on K Data Science, a popular machine learning site with more than 3 million views per month. Suggestions and reviews Click here if you have any reviews or suggestions. Page 2 Watch 16 Star 130 Fork 113 You Can't Perform This Action in It's time. You've signed up with another tab or window. Reboot to update the session. You subscribe to another tab or window. Reboot to update the session. We use the use of third-party analytical cookies to understand how you use GitHub.com so we can create the best products. Learn more. We use additional third-party analytical cookies to understand how you use GitHub.com so we can create the best products. You can always update your choices by clicking on Cookie Preferences at the bottom of the page. For more information, see us that we use important cookies to perform the main functions of a website, such as logging in. Find out more Always Active We use analytical cookies to understand how you use our websites so we can make them better, for example, they are used to gather information about the pages you visit and how many clicks you need to accomplish the task. Read more last update September 15, 2020. Keras is a powerful and easy-to-use free open source Python library to develop and evaluate deep learning models. It wraps up the effective theano and TensorFlow numerical computing libraries and allows you to identify and train neural network models in just a few lines of code. In this tutorial, you'll learn how to create your first model of a deep neural network in Python with Keras. Start your project with my new book Deep Learning with Python, including step-by-step tutorials and Python source code files for all examples. Start. February/2017 Update: An updated example of forecasting so rounding works in Python 2 and 3. Mar/2017 Update: An updated example for the latest versions of Keras and TensorFlow v2.0.0. Update Aug/2020: Updated for Keras v2.4.3 and TensorFlow v2.3. Develop your first neural network in Python with the PHi Whitehouse's Keras Step-By-StepPhoto, some rights reserved. Keras Tutorial Review There is not much code required, but we are going to step over it slowly, so you will know how to create your own models in the future. The steps you are going to cover in this tutorial are: Download the data. Identify the Keras model. Composite Keras Model. Check out the Keras model. Tie it all together. Make predictions This Keras tutorial has several requirements: You have a Python 2 or 3 installed and configured. You have SciPy (including NumPy) installed and configured. You have Keras and the backend (Theano or TensorFlow) installed and configured. If you need help with the environment, see tutorial: How to customize the Python environment for deep learning Create a new file called keras\_first\_network.py and enter or copy and paste code into the file, you're coming. Take my free 2-week email course and discover MLPs, CNNs and LSTMs (with the code). Click to sign up now and get a free version of the PDF Ebook course. Start a free mini-course right now! 1. Download data The first step is to identify the features and classes that we intend to use in this We will use the NumPy library to download our dataset, and we will use two classes from the Keras library to determine our model. The import required is below. The first neural network with keras tutorial of numpy import loadtxt from keras.models import Consistent from keras.layers import Dense ... In this Keras tutorial, we're going to use Pima Indians to start a diabetes dataset. This is a standard machine learning dataset from the UCI machine learning repository. It describes patient records for Pima Indians and whether they had developed diabetes within five years. Thus, it is a problem of binary classification (the onset of diabetes as 1 or not as 0). All input variables described by each patient are numerical. This simplifies the use directly with neural networks that expect numerical values of input and output, and is ideal for our first neural network in Keras. The dataset is available here: Dataset CSV File (pima-indians-diabetes.csv) Details of the dataset Download the dataset and place it in your local work catalog, in the same place as your python file. Save it with the name of the file: pima-indians-diabetes.csv pima-Indians-diabetes.csv Look inside the file, you should see the strings of data, as follows: 6.148,72.35,0,33.6,627.50,1,1.85,66.29,0,26.6,0.351,31.0,8,183,64.0,23.0,3.0,672.32,1,1.89,66,23,94,28,1,167,21.0,137,40,35,168,43,1.2,288,33.1, ... 6.148,72.35,0,33.6,627.50,1,1.85,66,29,0,26.6,0.351,31.0,8,183,64.0,23.0,3.0,672.32,1,1.89,66,23,94,28,1,167,21.0,137,40,35,168,43,1.2,288,33.1 We can now download the file as a number matrix using the NPMpy download function. There are eight input variables and one output variable (last column). We'll study the model for the X series map to the output variable (y), which we often summarize as y = f(x). Variables can be summarized as follows: Input variables (X): The number of times pregnant plasma glucose concentration 2 hours in the oral glucose tolerance test Diastolic blood pressure (mm Hg) Troiceps skin thickness (mm) 2-hour insulin serum (mu U/ml) Body mass index (weight per kg/ (height in m)) we can divide columns of data into variables. The data will be stored in a 2D array, where the first dimension is the strings, and the second dimension is columns, such as rows, columns. We can then select the output column (9th variable) through index 8. download the dataset into the dataset - loadtxt ('pima-indians-diabetes.csv', delimiter=',') and divide into input (X) and weekend (y) variables We are now ready to define our neural network model. Note that the dataset has 9 columns, and the 0:8 range will select columns from 0 to 7, stopping in front of index 8. If this is new to you, then you can learn more about the array of slicing and ranges in this post: How to index, slice and modify NumPy Arrays for machine learning in Python 2. Identify Keras Model models in Keras defined as a sequence of layers. We create successive models and add layers one at a time until we are happy with our network architecture. The first thing to do right is to make sure that the input layer has the right amount of input. This can be stated when you create the first layer with the input\_dim argument and set it up to 8 for 8 input variables. How do I know the number of layers and their types? This is a very difficult question. There are gurgistics that we can use, and often the best network structure is through the process of trial and error experiments (I'll explain more about it here). Typically, you need a network big enough to capture the structure of the problem. In this example, we'll use a fully connected network structure with three layers. Fully connected layers are defined by the Dense class. We can specify the number of neurons or nodes in the layer as the first argument, and specify the activation function using the activation argument. We'll use the corrected linear block activation function, called ReLU on the first two layers, and the Sigmoid function in the output layer. It used to be that Sigmoid and Tanh activation features were preferable to all layers. These days, the best performance is achieved with the ReLU activation feature. We use a sigmoid on the output layer to ensure our network output between 0 and 1 and easily compare either the probability of a Class 1 or a snap to a tight classification of any class with a default threshold of 0.5. We can put it all together by adding each layer: The model expects a string of data with 8 variables (argument input\_dim=8) The first hidden layer has 12 nodes and uses the relu activation function. The second hidden layer has 8 knots and uses the relu activation function. The output layer has one node and uses the function of sigmoid activation. ... -> define the model model\_keras -> successive () model.add(Dense(12, input\_dim=8, activation='relu')) model.add(Dense(8, activation='relu')) model.add(Dense(1, activation='sigmoid')) ... model.add(Dense(12, input\_dim=8, activation='relu')) model.add(Dense(8, activation='relu')) model.add(Dense(1, activation='sigmoid')) Note, the most confusing thing here is that the form of model input is defined as an argument on the first hidden layer. This means that the line of code that adds the first layer of Dense does two things, defining the input or visible layer and hidden layer. 3. Make a keras model Now that the model is defined, we can compose it. The model uses efficient numerical libraries under the lids (the so-called backend), such as Theano or TensorFlow. The backend automatically chooses the best way to present the network for training and forecasting to work on your hardware, such as a processor or GPU, or even distributed. When compiling, we must specify some of the additional properties required when learning the network. Keep in mind that learning the network means finding the best set of weights for the input map for the conclusions in our dataset. We must specify the loss function to use to evaluate the weight gain, the optimizer used to search through different weights for the network and any additional metrics we would like to collect and report during training. In this case, we will use cross entropy as a loss argument. This loss is for binary classification problems and is defined in Keras as binary\_crossentropy. You can learn more about the choice of loss functions based on your problem here: How to choose loss functions when learning deep neural network learning We will define the optimizer as an effective algorithm of stochastic gradient descent adam. This is a popular version of the gradient descent because it automatically adjusts itself and gives good results in a wide range of problems. To learn more about Adam's version of the stochastic gradient descent, see the post: A gentle introduction to Adam's algorithm for deep learning Finally, because it's a classification problem, we'll collect and report on the accuracy of the classification determined by argument metrics. compilation of the keras model model.compile (binary\_crossentropy, binary\_crossentropy, ...) -> Fit Keras Model We defined our model and made it ready for efficient computing. Now it's time to run a model on some data. We can train or place our model on our downloaded data by calling the function fit () on the model. Training takes place in different eras, and each era is divided into parties. Epoch: One runs through all the lines in the training data set. Package: One or more samples reviewed by the model during the era before the weights were updated. One era consists of one or more parties based on the chosen size of the party and the model is suitable for each era. For more information on the difference between eras and parties, see the post: What is the difference between a package and an era in a neural network? The learning process will take place for a fixed number of iterations through a data set called the epochs that we must specify using the argument of epochs. We must also set the number of dataset lines that are considered before updating the scale of the model during each era, called batch size and set using batch\_size argument. To solve this problem will work for a small number of eras (150) and use Small batch size 10. These configurations can be selected experimentally by trial and error. We want to train the model enough to recognize a good (or good enough) display of input lines in the output classification. The model will always have some errors, but the number of errors will be leveled after some point for a given model configuration. This is called the convergence of models. - fits the keras model on the dataset model.fit (X, y, epochs=150, batch\_size=10) batch\_size ... You don't need a GPU for this example, but if you're interested in how to cheaply run large models on GPU hardware in the cloud, see this post: How to set up Amazon AWS EC2 graphics processors to train Keras Deep Learning Models 5. Evaluate the Keras Model We have trained our neural network throughout the data set and can evaluate network performance on one data set. This will only give you an idea of how well we have washed away the data set (such as train accuracy), but don't know how well the algorithm can work on the new data. We did this for simplicity, but ideally you could split your data into data sets to train and evaluate your model. You can evaluate your model in the training dataset using the evaluation function on the model and pass it on to the same input and output that are used to train the model. This will create a forecast for each pair of input and output data and collect points, including average losses and any customized metrics such as accuracy. The evaluation function returns a list with two values. First, the loss of the model in the dataset, and the second will be the accuracy of the model on the data set. We are only interested in reporting on accuracy, so we will ignore the loss of value. Keras model score, accuracy and model.assessment (X, y) printing (Precision: .2F % (accuracy 100) - Keras model\_score, accuracy and model.assessment (X, y)print (Precision: .2F % (accuracy 100)) 6. Tie It All Together You have just seen how you can easily create your first neural network model in Keras. Let's link all this to a complete example of code. The first neural network with keras-textbook from numpy import loadtxt from keras.models import Dense and downloads a data set - loadtxt ('pima-indians-diabetes.csv', delimiter=',') - divided into input (X) and weekend (y) variables X - dataset:0:8 u dataset:8 to define the model of keras - sequential () model.add (Dense (12, input\_dim=8, activation='relu')) model.add (Dense (8, activation='relu')) model.add (Dense (1, activation='sigmoid')) - a compilation of the model keras model.compile (loss='binary\_crossentropy', optimizer='adam', metrics='accuracy') - fit models Keras on the model of the dataset.fit (X, y, epochs=150, batch\_size=10) - evaluate the model of keras, accuracy and model. The first neural network with keras tutorial from numpy import loadtxt from keras.models import Dense dataset - loadtxt ('pima-indians-diabetes.csv', delimiter=',') input\_dim=8, activation='relu')) model.add (Dense (8, activation='relu')) model.add (Dense (1, activation='sigmoid')) compilation keras model.compile (loss='binary\_crossentropy', optimizer='adam', metrics=accuracy) fit models keras on datasetmodel.fit (y, epochs=150, batch\_size=10) estimate keras model\_accuracy and model.assessment (X, y)Print (Accuracy: .2F % (accuracy 100)) you can copy the entire code into the Python file and save it as keras\_first\_network.py in the same catalog as the pima-indians-diabetes.csv. You can then run the Python file as a script from the command line (team query) as follows: python keras\_first\_network.py Running this example, you should see the message for each of the 150 eras of print loss and accuracy, and then the final assessment of the trained model on the training data set. It takes about 10 seconds to perform on my workstation running on the CPU. Ideally, we would like the losses to go to zero and the accuracy to 1.0 (e.g. 100%). 768/768 [=====] - Os 63us/step - loss: 0.4730 - acc: 0.7747 Epoch 147/150 768/768 [=====] - Os 63us/step - loss: 0.4764 - acc: 0.7747 Epoch 148/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 149/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 150/150 768/768 [=====] - Os 63us/step - loss: 0.4754 - acc: 0.7799 768/768 [=====] - Os 63us/step - loss: 0.4730 - acc: 0.7747 Epoch 151/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 152/150 768/768 [=====] - Os 64us/step - loss: 0.4764 - acc: 0.7747 Epoch 153/150 768/768 [=====] - Os 63us/step - loss: 0.4730 - acc: 0.7747 Epoch 154/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 155/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 156/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 157/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 158/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 159/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 160/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 161/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 162/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 163/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 164/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 165/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 166/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 167/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 168/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 169/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 170/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 171/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 172/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 173/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 174/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 175/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 176/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 177/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 178/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 179/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 180/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 181/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 182/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 183/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 184/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 185/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 186/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 187/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 188/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 189/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 190/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 191/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 192/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 193/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 194/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 195/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 196/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 197/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 198/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 199/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 200/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 201/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 202/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 203/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 204/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 205/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 206/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 207/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 208/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 209/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 210/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 211/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 212/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 213/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 214/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 215/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 216/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 217/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 218/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 219/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 220/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 221/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 222/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 223/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 224/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 225/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 226/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 227/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 228/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 229/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 230/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 231/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 232/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 233/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 234/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 235/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 236/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 237/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 238/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 239/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 240/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 241/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 242/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 243/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 244/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 245/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 246/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 247/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 248/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 249/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 250/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 251/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 252/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 253/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 254/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 255/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 256/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 257/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 258/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 259/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 260/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 261/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 262/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 263/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 264/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 265/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 266/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 267/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 268/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 269/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 270/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 271/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 272/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 273/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 274/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 275/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 276/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 277/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 278/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 279/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 280/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 281/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 282/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 283/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 284/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 285/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 286/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 287/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 288/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 289/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 290/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 291/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 292/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 293/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 294/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 295/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 296/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 297/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 298/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 299/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 300/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 301/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 302/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 303/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 304/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 305/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 306/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 307/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 308/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 309/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 310/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 311/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 312/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 313/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 314/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 315/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 316/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch 317/150 768/768 [=====] - Os 64us/step - loss: 0.4730 - acc: 0.7747 Epoch 318/150 768/768 [=====] - Os 63us/step - loss: 0.4737 - acc: 0.7682 Epoch

